

Brushless Flat DC-Micromotors

4 Pole Technology

0,5 mNm
1,5 W

Series 1509 ... B

Values at 22°C and nominal voltage		1509 T	006 B	012 B	
1	Nominal voltage	U_N	6	12	V
2	Terminal resistance, phase-phase	R	22	92,7	Ω
3	Efficiency, max.	η_{max}	54	53	%
4	No-load speed	n_0	15 000	14 900	min^{-1}
5	No-load current, typ. (with shaft \varnothing 1,5 mm)	I_0	0,019	0,009	A
6	Stall torque	M_H	0,953	0,904	mNm
7	Friction torque, static	C_0	0,019	0,019	mNm
8	Friction torque, dynamic	C_V	$3,42 \cdot 10^{-6}$	$3,42 \cdot 10^{-6}$	$\text{mNm}/\text{min}^{-1}$
9	Speed constant	k_n	2 682	1 339	min^{-1}/V
10	Back-EMF constant	k_E	0,373	0,747	$\text{mV}/\text{min}^{-1}$
11	Torque constant	k_M	3,56	7,13	mNm/A
12	Current constant	k_I	0,281	0,14	A/mNm
13	Slope of n-M curve	$\Delta n/\Delta M$	16 577	17 423	$\text{min}^{-1}/\text{mNm}$
14	Terminal inductance, phase-phase	L	570	2 282	μH
15	Mechanical time constant	τ_m	120	126	ms
16	Rotor inertia	J	0,69	0,69	gcm^2
17	Angular acceleration	α_{max}	14	13	$\cdot 10^3 \text{rad}/\text{s}^2$
18	Thermal resistance	R_{th1} / R_{th2}	65 / 45		K/W
19	Thermal time constant	τ_{w1} / τ_{w2}	12 / 133		s
20	Operating temperature range:				
	- motor		-25 ... +80		$^{\circ}\text{C}$
	- winding, max. permissible		+80		$^{\circ}\text{C}$
21	Shaft bearings		ball bearings, preloaded		
22	Shaft load max.:				
	- with shaft diameter		1,5		mm
	- radial at 3 000 min^{-1} (3 mm from mounting flange)		2		N
	- axial at 3 000 min^{-1} (push only)		2		N
	- axial at standstill (push only)		15		N
23	Shaft play:				
	- radial	\leq	0,015		mm
	- axial	$=$	0		mm
24	Housing material		plastic		
25	Mass		6,9		g
26	Direction of rotation		electronically reversible		
27	Speed up to	n_{max}	40 000		min^{-1}
28	Number of pole pairs		2		
29	Hall sensors		digital		
30	Magnet material		NdFeB		
Rated values for continuous operation					
31	Rated torque	M_N	0,45	0,44	mNm
32	Rated current (thermal limit)	I_N	0,147	0,071	A
33	Rated speed	n_N	5 860	5 550	min^{-1}

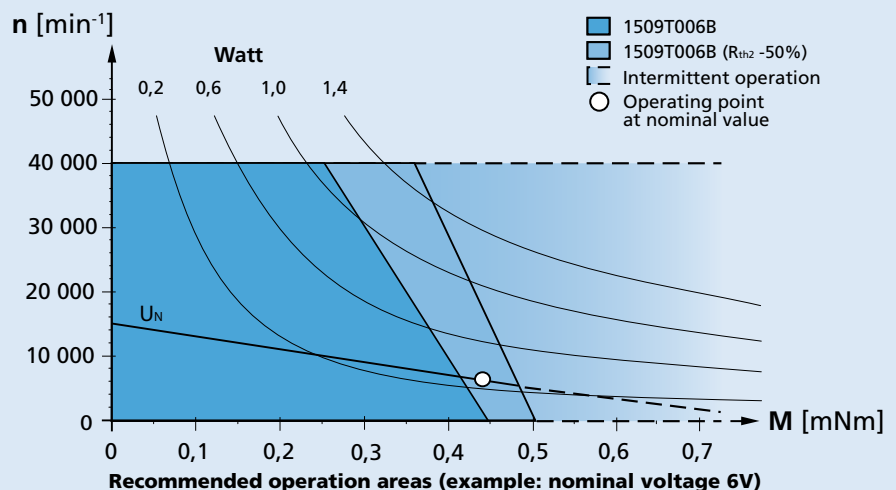
Note: Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The R_{th2} value has been reduced by 25%.

Note:

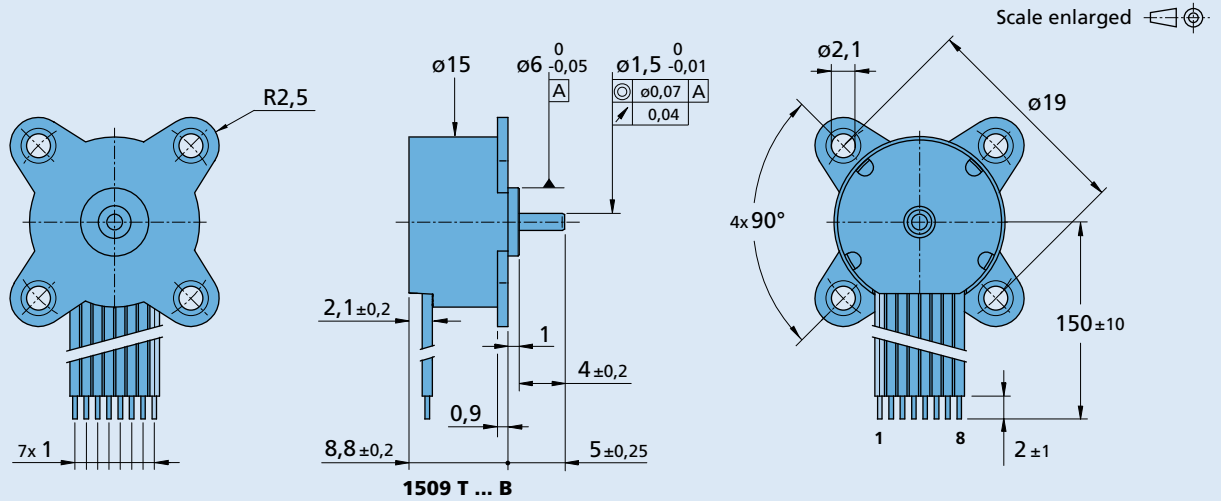
The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition (R_{th2} 50% reduced).

The nominal voltage (U_N) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



Dimensional drawing



Option, cable and connection information

Example product designation: **1509T006B-X4192**

Option	Type	Description	Connection	
X4192	Bearing lubrication	For vacuum of 10^{-7} Torr @ 20°C	No.	Function
4082	Temperature range	Extended temperature range (-40...+85°C)	1	Phase C
			2	Phase B
			3	Phase A
			4	GND
			5	U _{DD} (+5V)
			6	Hall sensor C
			7	Hall sensor B
			8	Hall sensor A
			Standard cable	
			Insulation: PVC	
			8 conductors, AWG 28	
			pitch 1 mm, wires tinned	

Product Combination

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
		SC 1801	